

# Partial solvers for generalized parity games

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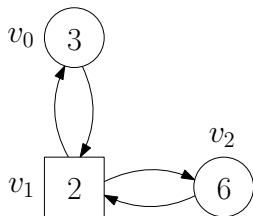
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## Game structure and play

**Game structure**  $G = (V_0, V_1, E)$  and **priority function**  $\alpha: V \rightarrow \{0, 1, \dots, d\}$



**Play:** infinite path in  $G$  starting in  $v_0$   
 $\rightarrow$  sequence of priorities corresponding to  $\pi$

**Example:**

$$\pi = v_0 v_1 v_2 (v_1 v_0)^\omega$$

$$\alpha(\pi) = 3 \ 2 \ 6 \ (2 \ 3)^\omega$$

$\rightarrow$  play **won** by player 1

**Objective** for player  $i \in \{0, 1\}$ : set of plays  $\Omega_i \subseteq V^\omega$

- $\Omega_0 = 0\text{Parity}(\alpha)$ : plays where maximum priority seen infinitely often is **even**
- $\Omega_1 = 1\text{Parity}(\alpha)$ : plays where maximum priority seen infinitely often is **odd**

**Strategies:** **memoryless** strategies required for both players to win

**Complexity:**  $\text{NP} \cap \text{coNP}$  [2] and  $\text{UP} \cap \text{coUP}$  [6], P membership is open problem

## Reactive synthesis from LTL specifications

Parity games are **intermediary steps** in reactive synthesis from LTL specifications [7]

**Goal** : given an environment, synthesise a system that respects specifications (LTL)

**Input** : an LTL formula  $\phi$  whose propositional variables are partitioned into inputs (controllable by the environment) and outputs (controlled by the system)

**Classical algorithm** :

- construct a deterministic parity automaton (DPA)
- the DPA can then be seen as a two player graph game
- winning condition in this game : parity acceptance condition of the DPA

**Particularity**: LTL formula  $\phi = \phi_1 \wedge \dots \wedge \phi_n$  is a **conjunction of smaller formulas**

- compositional approach: construct a DPA  $A_i$  **for each** subformula  $\phi_i$
- underlying game is then the product of the automata  $A_i$  and the winning condition is a **conjunction (for Player 0) of parity conditions**

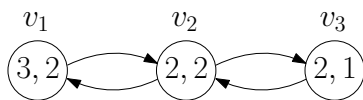
→ such games are **generalized parity games**

## Generalized parity objective

Now consider  $k \geq 1$  priority functions  $\alpha_\ell : V \rightarrow \{0, \dots, d_\ell\} \forall \ell \in \{1, \dots, k\}$   
 → we consider **several sequences of priorities** corresponding to a play

Objective  $\Omega_0 = \text{ConjEvenParity}(\alpha_1, \dots, \alpha_k)$ , **conjunction** of parity objectives  
 → maximum priority seen infinitely often **according to every function** is **even**

Opposite  $\Omega_1 = \text{DisjOddParity}(\alpha_1, \dots, \alpha_k)$ , **disjunction** of parity objective  
 → maximum priority seen infinitely often **according to some function** is **odd**



$$\pi = v_1 (v_2 v_3)^\omega$$

$$\alpha_1(\pi) = 3 (2 2)^\omega$$

$$\alpha_2(\pi) = 2 (2 1)^\omega$$

**Strategies:** player 0 requires a **finite-memory strategy** to win

**Complexity:** coNP – *complete* [1]

## Partial solvers

Algorithms used to solve (generalized) parity games have **exponential complexity**

- introduction of **incomplete** algorithms that **partially solve** parity games
- benefit: partial solvers are **polynomial-time** algorithms [3, 4, 8]
- experimentally shown to **behave well** on random benchmarks and completely solve structured benchmarks from PGSolver [3]

Formally, a partial solver returns

- **subsets of winning nodes**  $Z_0 \subseteq \text{Win}(G, 0, \Omega_0)$  and  $Z_1 \subseteq \text{Win}(G, 1, \Omega_1)$
- a sub-game  $G \setminus (Z_0 \cup Z_1)$  **that is unsolved**

Our contributions

- **extend** three partial solvers for parity games to generalized parity games
- **combine** partial solvers with recursive complete algorithms [9, 1]
- **evaluate** on benchmarks generated from LTL formulas

Let us now give intuitions on how two of them work !

## Partial solver using Büchi games

A first very simple partial solver based on Büchi and safety objectives

Based on a simple remark for player 0 (symmetric for player 1)

- if player 0 can ensure to visit infinitely often an even priority
- without visiting a greater odd priority
- then he is winning for  $0\text{Parity}(\alpha)$

Given  $p \in \{0, \dots, d\}$  an even priority, we want to

- visit  $U = \{v \in V \mid \alpha(v) = p\}$  infinitely often:  $\text{Buchi}(U)$
- avoid  $U' = \{v \in V \mid \alpha(v) \text{ is an odd priority and } \alpha(v) > p\}$ :  $\text{Safe}(U')$

### Conjunction of Büchi and safety objectives

If  $v \in \text{Win}(G, 0, \text{Buchi}(U) \cap \text{Safe}(U'))$ , then  $v \in \text{Win}(G, 0, 0\text{Parity}(\alpha))$ .

Variant : property holds with  $\text{CoBuchi}(U')$  instead of  $\text{Safe}(U')$

## Partial solver using generalized Büchi games

Adaptation to generalized parity games based on **generalized Büchi** objective

Player 0 with the **conjunction** of parity objectives, **on all dimensions  $l$**  he wants

- to ensure to visit infinitely often an even priority  $p_l$
- without visiting an odd priority greater than  $p_l$
- if he does, he is winning for  $\text{ConjEvenParity}(\alpha_1, \dots, \alpha_k)$

→ this is **Generalized Büchi objective** using  $k$  sets  $U_l = \{v \in V \mid \alpha_l(v) = p_l\}$

Player 1 with the **disjunction** of parity objectives, **on some dimensions  $l$**

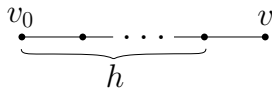
- if he ensures  $\text{1Parity}(\alpha_l)$ , he satisfies the disjunction

→ can apply **same property** as before **dimension by dimension**

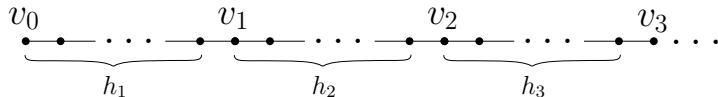
## Partial solver : Good Episode

**GoodEpSolver** [4] for parity games : remark for player 0 (symmetric for player 1)

- if player 0 can ensure to visit some node  $v$  from  $v_0$  :  $hv$
  - such that the maximum visited priority in  $h$  is even
- $h$  is a **good episode**



If a play consists in a succession of good episodes, it is won by player 0



Maximum priority in each  $h_j$  is even → objective  $0\text{Parity}(\alpha)$  is satisfied

To compute these good episodes, introduce an **extended game structure**  $G \times M$

→ records the maximal visited priority **by construction**

- compute a fixpoint  $\text{GoodEp}_0(G, \alpha)$  based on attractor computations
- from the fixpoint, player 0 can **ensure a succession of good episodes**



## Generalized Good episodes & other contributions

The generalized version computes a specific fixpoint **depending on the player**

- player 0: **extended game structure**  $G \times M_1 \times \dots \times M_k$
- player 1: **previous approach** :  $\text{GoodEp}_1(G, \alpha_\ell)$  for some dimension  $\ell$

**Explicit construction** and **attractor computation** in extended game  $G \times M$  is **costly**  
→ work symbolically using **antichains-based algorithm** to reduce required space

Additional contributions:

- we adapted a third partial solver [3] to generalized parity games
- partial solvers can be combined with the **recursive algorithm** for (generalized) parity games [9, 1] to obtain complete solvers
- implemented 6 algorithms and their combination with recursive algorithms
- evaluated on benchmarks **generated from meaningful LTL specifications** [5]

## Results for parity games

240 benchmarks with mean size  $|V|$  of around 46K and maximal size of 3157K, and a mean number  $d$  of priorities of 4.1 with a maximal number  $d = 15$

Solver	Solved	T.O.	Fastest	Mean time (233)
Zielonka	240 (100%)	0	150 (62 %)	272 ms
Ziel&BuchiSolver	240 (100%)	0	89 (37 %)	480 ms
Ziel&GoodEpSolver	233 (97%)	7	0 (0%)	1272 ms
Ziel&LaySolver	238 (99%)	2	1 (1%)	587 ms
BuchiSolver	203 (84%) - 37	0	-	-
GoodEpSolver	233 (97%) - 0	7	-	-
LaySolver	232 (97%) - 6	2	-	-

- recursive algorithm is **faster than partial solvers on average** which was not observed on random graphs in [4]
- the **combination** of partial solvers with the recursive algorithm **improves its performances** in 90 cases over 240 (38%)

## Results for generalized parity games

152 benchmarks with mean size  $|V|$  of around 207K and maximal size of 709K, mean number of priority functions is 4.53 and maximum number is 17.

Solver	Solved	T.O.	Fastest	Mean-Time (87)
GenZielonka	128 (84%)	24	33 (25%)	66 ms
GenZiel&GenBuchiSolver	130 (86%)	22	72 (55%)	56 ms
GenZiel&GenGoodEpSolver	112 (74%)	40	24 (18%)	644 ms
GenZiel&GenLaySolver	110 (72%)	42	3 (2%)	1133 ms
GenBuchiSolver	110 (72%) - 20	22	-	-
GenGoodEpSolver	112 (74%) - 0	40	-	-
GenLaySolver	104 (68%) - 6	42	-	-

- some benchmarks **can't be solved** by generalized recursive algorithm or a partial solver alone, but can be solved by the combination of the generalized recursive algorithm with a partial solver
- the **combination** of partial solvers with the generalized recursive algorithm improves its performances in 99 cases over 132 (75%)

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